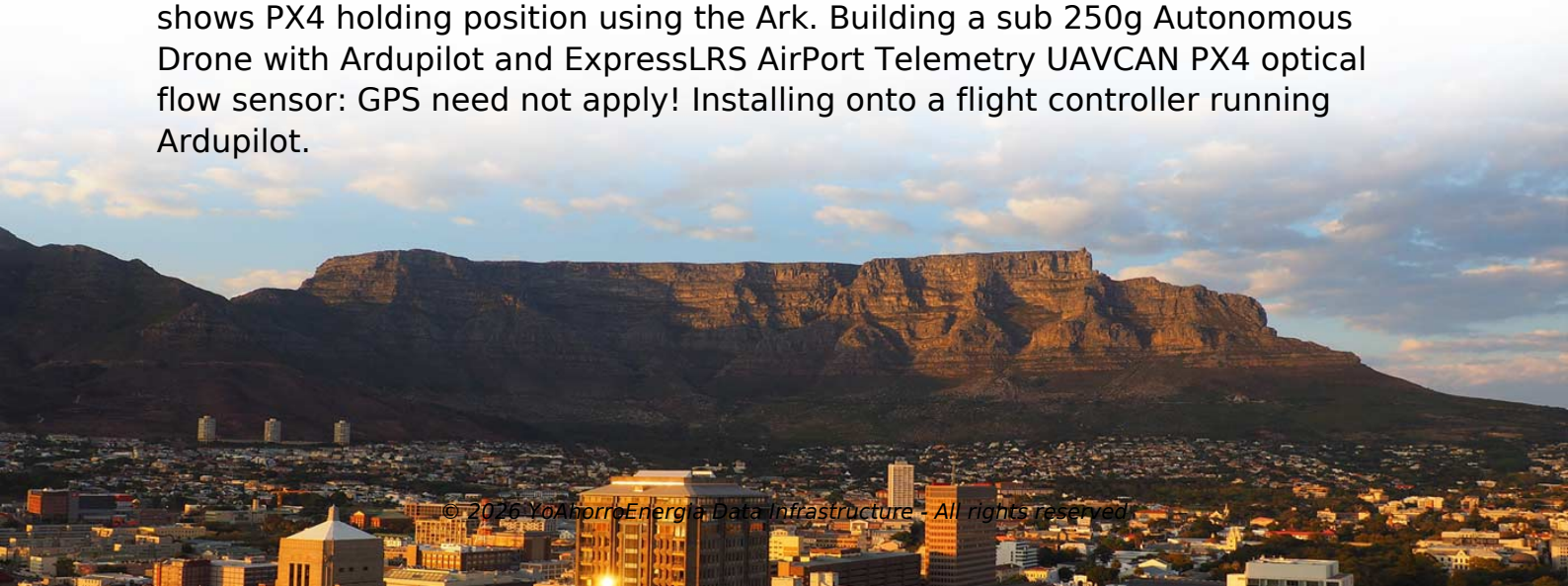
How to use the px4flow optical flow module

Overview

The easiest way to calculate the optical flow is to use the PX4Flow board. This article describes how to setup the PX4FLOW (Optical Flow) Sensor which can be used for Non-GPS navigation. The PX4FLOW is not yet supported in Plane or Rover. It can be used to determine speed when navigating without GNSS — in buildings, underground, or in any other GNSS-denied environment. Unlike many mouse sensors, it also works indoors and in low outdoor light conditions without the need. Optical Flow uses a downward facing camera and a downward facing distance sensor for position estimation. The video below shows PX4 holding position using the Ark. Building a sub 250g Autonomous Drone with Ardupilot and ExpressLRS AirPort Telemetry UAVCAN PX4 optical flow sensor: GPS need not apply! Installing onto a flight controller running Ardupilot.



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The document provides information about the PX4Flow smart camera, including its features, specifications, connectors, and assembly instructions. Key points include: - It is an optical flow ...

In order to ensure good optical flow quality, it is important to focus the camera on the PX4Flow to the desired height of flight. To focus the camera, put an object with text on (e. g. a book) and plug in the ...

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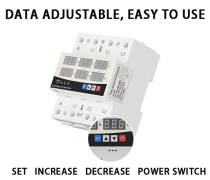

Get started with the PX4FLOW v1.3 optical flow smart camera. This quick start guide provides essential information on setup, features, and specifications.

On the ground station interface, select "Initial Settings" -> "Optional Hardware" -> "PX4Flow Optical Flow" Align the lens to about 3m and adjust the lens focal length to make the image clearest.

PX4Flow is an optical flow smart camera. It has a native resolution of 752×480 pixels and calculates optical flow on a 4x binned and cropped area at 250 Hz (bright, outdoors), giving it a very high light ...

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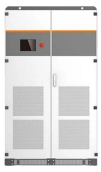

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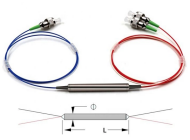

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	Installing onto a flight controller running Ardupilot.Read this before attempting installation: ...

Contact Us

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